# Flow in Conjugate **Natural Circulation Loops**

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Two natural circulation loops are considered thermally coupled through a heat exchanger common to both. Over the rest of the loops, the heat inflow per unit length is assumed known. A steady-state analysis is made in order to determine the fluid velocities and temperature distributions. Certain general results can be obtained for loops of arbitrary shapes. The special case of square geometries is also considered. The possibility of four different steady-state conditions is demonstrated and the variation of these solutions with respect to the system

#### Nomenclature

parameters is discussed.

c	= specific heat of the fluid
D	= cross-sectional diameter
g	= acceleration due to gravity
$egin{array}{c} g \ \widetilde{g} \ I \end{array}$	= local component of gravitational acceleration
	= defined in Eq. (16)
1	= nondimensional total length
L	= total length of loop
$l_c$	= length of heat exchanger zone
q	= heat inflow per unit length
$q_M$	= maximum absolute value of $q$
Q	= nondimensional heat inflow
S	= nondimensional longitudinal coordinate
T	= fluid temperature
$T_0$	= reference temperature
и	= fluid longitudinal velocity
$\boldsymbol{U}$	= overall heat transfer coefficient
$\boldsymbol{v}$	= nondimensional fluid velocity
V	= harmonic mean of $v_1$ and $v_2$
X	= longitudinal coordinate
β	= coefficient of thermal expansion
Γ	= Rayleigh number
δ	= nondimensional gravitational component
heta	= nondimensional temperature
ν	= kinematic viscosity of fluid
ρ	= fluid density at reference temperature
Subscripts	
1	= first loop
2	= second loop

# I. Introduction

PROGRESS has been made in the understanding of natural convection loops of arbitrary geometry with one-dimensional models, a recent review of which appears in Ref. 1. Industrial and other applications, however, make use of variations of such simple systems. One example is the multiple loop system<sup>2,3</sup> in which the fluid moves through interconnected pipes much like an electrical network. Another possibility is the conjugate loop system in which a number of natural circulation loops are physically separate but thermally coupled through heat exchangers. Such types of systems will be discussed in this paper.

Nuclear reactor design makes use of circulation systems based on natural convection, especially with regard to emergency cooling.<sup>4,5</sup> Our interest here is in the conjugate system of the kind described by Grand,6 considerably simplified in order to permit analysis. Although the discussion in Ref. 6 is directed mainly toward problems associated with a liquid metal fast breeder reactor, many of the considerations apply equally well to light water reactors. The residual heat generated after reactor shutdown is designed to be removed by a normal and a decay heat removal system. In both cases, an intermediate heat exchanger transfers heat from the primary heat-generating loop to a secondary loop. This secondary loop can be either the normal operating system, in which case heat rejection would be to the steam generators, or a special system releasing heat to the atmosphere through an air-heat exchanger. In the present analysis, we will assume that the two loops are operating on natural circulation conditions.

Actual designs can be quite complicated in terms of shape and the number of thermally coupled loops. We will simplify the analysis by considering only two loops with a convective heat exchanger zone. However, fluid properties in the loops can be entirely different.

### II. Formulation of the Problem

We consider two closed loops of arbitrary shapes, each of which has constant but different circular cross sections. The working fluids can also be taken to be different. There is a coupling zone through which they exchange heat, but not mass or momentum. Such a conjugate system is shown in Fig. 1. A one-dimensional flow approximation will be made in the governing equations, which have been well discussed in the literature for the single loop. We will deal with steady-state conditions under the Boussinesq approximation and neglect axial heat conduction.

The constituent loops of the system will be referred to by the subscripts 1 and 2. The origin of coordinates is taken at one extreme of the heat exchanger zone, with  $x_1$  and  $x_2$  being the

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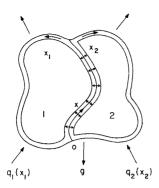


Fig. 1 Arbitrary conjugate loop system.

respective longitudinal coordinates along each of the loops. In the exchanger, the loops are assumed to coincide so that in this interval we can use a common coordinate x. This also means that the local gravity functions for both loops coincide in this zone

Mass conservation in a loop of constant area and density means that the fluid velocity  $u_i$  should be a constant. The momentum equation integrated over the entire loop i is<sup>7</sup>

$$\frac{32\nu_i}{D_i}u_i = \frac{\beta_i}{L_i} \int_0^{L_i} \tilde{g}_i(x_i)T_i(x_i) dx_i$$
 (1)

where  $v_i$  is the kinematic viscosity of the fluid,  $D_i$  the diameter,  $\beta_i$  the coefficient of thermal expansion,  $\tilde{g}_i(x_i)$  the gravitational acceleration in the negative  $x_i$  direction,  $L_i$  the total length of the loop, and  $T_i(x_i)$  the temperature, all for the loop i. For simplicity, the viscous force in the left-hand side of this equation has been taken to correspond to Poiseuille flow in a straight pipe, but other power-law relations between the friction factor and the Reynolds number may be easily taken into account. The right-hand side of the equation is the total buoyancy force over the whole loop. Integration of the momentum equation over the loop has been used to eliminate the pressure force term.

In order to write the energy equation we will assume that the rate of heat transfer in the exchanger zone is proportional to the local temperature difference between the fluids in the loops; that for the rest of the lengths is prescribed. Thus,

$$\rho_{i}c_{i}u_{i}\frac{\mathrm{d}T_{i}}{\mathrm{d}x_{i}} = \begin{cases} \frac{4U_{i}}{D_{i}}(T_{j} - T_{i}) & \text{for} & 0 < x_{i} \leq L_{c} \\ \\ \frac{4q_{i}}{\pi D_{i}^{2}} & \text{for} & L_{c} < x_{i} \leq L_{i} \end{cases}$$
(2)

where  $\rho i$  is the fluid density,  $c_i$  the specific heat,  $L_c$  the length of the exchanger section,  $U_i$  the overall heat transfer coefficient in the exchanger, and  $q_i(x_i)$  the heat inflow per unit length over the rest of the loop. The indices i and j refer to different loops, so that we must take i=1, j=2 to obtain the equation for one loop and i=2, j=1 for the other. By energy conservation in the exchanger, we must have  $U_1D_1=U_2D_2$ .

We now have four equations with the same number of unknowns  $u_1$ ,  $u_2$ ,  $T_1(x_1)$ , and  $T_2(x_2)$ . Nondimensionalization will be carried out using the following variables:

$$\delta_{i} = \tilde{g}_{i}(x_{i})/g$$

$$s_{i} = x_{i}/L_{c}$$

$$\Delta T_{i} = q_{iM}/U_{i}L_{c}$$

$$\theta_{i}(x_{i}) = [T_{i}(x_{i}) - T_{0}]/\Delta T_{i}$$

$$\begin{aligned} v_i &= u_i \rho_i c_i D_i / 4 U_i L_c \\ l_i &= L_i / L_c \\ \Gamma_i &= \beta_i g \Delta T_i \rho_i c_i D_i^3 / 128 U_i L_i \nu_i \\ Q_i &= q_i / \pi U_i \Delta T_i D_i \end{aligned}$$

where  $\delta_{i}$ ,  $s_{i}$ ,  $\theta_{i}$ ,  $v_{i}$ ,  $l_{p}$  and  $Q_{i}$  are the nondimensional gravitational acceleration component, longitudinal coordinate, temperature, velocity, loop total length, and heat inflow, respectively.  $\Gamma_{i}$  is a modified Rayleigh number that represents the heat flux in each loop. With these variables, Eqs. (1) and (2) become

$$v_i = \Gamma_i \int_0^{l_i} \delta_i(s_i) \theta_i(s_i) \mathrm{d}s_i \tag{3}$$

and

$$v_{i} \frac{\mathrm{d}\theta_{i}}{\mathrm{d}s_{i}} = \begin{cases} \theta_{j} - \theta_{i} & \text{for } 0 < s_{i} < 1 \\ Q_{i}(s_{i}) & \text{for } 1 < s_{i} < l_{i} \end{cases}$$
(4)

in terms of the nondimensional velocity  $v_i$  and temperature field  $\theta_i(x_i)$ . The gravitational function satisfies the geometrical relation

$$\int_0^{l_i} \delta_i(s_i) \, \mathrm{d}s_i = 0 \tag{5}$$

which will be used later. In the heat exchanger section,  $\delta_i(x_i)$  is the same for both loops.

The total heat entering the system should obviously be zero for steady-state solutions to exist. That this is reflected in the governing equations is shown by integrating Eq. (4) for both loops and then adding the results. We obtain

$$\int_{1}^{l_{1}} Q_{1}(s_{1}) ds_{1} + \int_{1}^{l_{2}} Q_{2}(s_{2}) ds_{2} = 0$$
 (6)

#### III. General Results

Equations (3) and (4) can be reduced to two transcendental equations in the fluid velocities. To do this, we will first integrate the energy equations to determine the temperature distributions in terms of the velocities and then substitute the results in the momentum equation.

In the exchanger zone  $(s_i < 1)$ , the coordinates  $s_1$  and  $s_2$  are identical and can be replaced by s. Adding Eq. (4) for i = 1 and i = 2 in this interval and integrating, we get

$$v_1\theta_1(s) + v_2\theta_2(s) = v_1\theta_1(0) + v_2\theta_2(0) \tag{7}$$

where the constant of integration has been determined at s = 0. From this, we can obtain one temperature field in terms of the other. Substituting this result in Eq. (4), we get for each loop

$$\frac{\mathrm{d}\theta_i}{\mathrm{d}s} + \frac{\theta_i}{v} = \frac{v_i \theta_i(0) + v_j \theta_j(0)}{v_i v_j} \qquad \text{for} \qquad 0 < s < 1$$
 (8)

where

$$V = \frac{v_1 v_2}{v_1 + v_2}$$

This can be integrated to give

$$\theta_{i}(s) = \frac{1}{v_{i} + v_{j}} \left\{ v_{i} \theta_{i}(0) + v_{j} \theta_{j}(0) + v_{j} [\theta_{i}(0) - \theta_{j}(0)] \exp(-s/V) \right\}$$
 for  $0 < s < 1$  (9)

The temperatures at the end of the exchanger are  $\theta_1(1)$  and  $\theta_2(1)$ , obtained from Eq. (9). The rest of the energy equation (4) can now be integrated from this point on. We get

$$\theta_i(s_i) = \theta_i(1) + \frac{1}{v_i} \int_1^{s_i} Q_i(s_i^{'}) ds_i^{'}$$
 for  $1 < s_i < l_i$  (10)

Since on completing the loop, the temperature should again be  $\theta_i(0)$ , we have the following relation:

$$\theta_i(0) = \theta_i(1) + \frac{1}{v_i} \int_1^i Q_i(s_i') ds_i'$$
 (11)

From this equation applied to both loops and using Eq. (6), we get

$$\theta_1(0) - \theta_2(0) = \frac{1}{V} \left[ 1 - \exp(-1/V) \right]^{-1} \int_0^h Q_1(s_1) \, ds_1$$
 (12)

This relates the temperature of the loops at their origins, showing that they are not independent.

The temperature fields found in Eqs. (9) and (10) can be substituted in Eq. (3) to give

$$v_{i} = \frac{\Gamma_{i}v_{j}}{v_{i} + v_{j}} [\theta_{i}(0) - \theta_{j}(0)] \left[ \int_{0}^{1} \delta(s) \exp(-s/V) \, ds \right]$$

$$+ \exp(-1/V) \int_{1}^{h} \delta_{i}(s_{i}) \, ds_{i}$$

$$+ \frac{\Gamma_{i}}{v_{i}} \int_{1}^{h} \delta_{i}(s_{i}) \int_{1}^{s_{i}} Q_{i}(s_{i}') \, ds_{i}'$$

$$(13)$$

where we have used condition (5). On substituting Eq. (12) and multiplying by  $v_i/\Gamma_b$  we have

$$\frac{v_i^2}{\Gamma_i} = \left[1 - \exp(-1/V)\right]^{-1} \int_1^h Q_i(s_i) \, \mathrm{d}s_i$$

$$\left[ \int_0^1 \delta(s) \, \exp(-s/V) \, \mathrm{d}s \right]$$

$$+ \exp(-1/V) \int_1^h \delta_i(s_i) \, \mathrm{d}s_i$$

$$+ \int_1^h \left[\delta_i(s_i) \int_1^{s_i} Q_i(s_i') \, \mathrm{d}s_i'\right] \, \mathrm{d}s_i$$
(14)

We have now obtained the two simultaneous transcendental equations that should be solved for specific heating and gravity functions in order to determine the fluid velocities.

On adding Eq. (14) for the two loops and using Eq. (6), we get

$$I = \frac{v_1^2}{\Gamma_1} + \frac{v_2^2}{\Gamma_2} \tag{15}$$

where

$$I = \int_{1}^{t_{1}} \delta_{1}(s_{1}) \int_{1}^{s_{1}} Q_{1}(s_{1}') ds_{1}' ds_{1}$$

$$+ \int_{1}^{t_{2}} \delta_{2}(s_{2}) \int_{1}^{s_{2}} Q_{2}(s_{2}') ds_{2}' ds_{2}$$
(16)

We have used the fact that

$$\int_{1}^{t_{1}} \delta_{1}(s_{1}) ds_{1} + \int_{1}^{t_{2}} \delta_{2}(s_{2}) ds_{2} = 0$$
 (17)

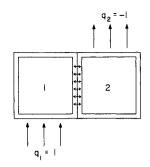


Fig. 2 Thermally coupled square loops.

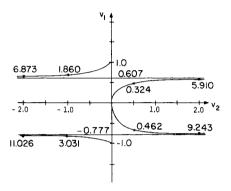


Fig. 3  $v_1-v_2$  plot for  $\Gamma_1=1$  and different  $\Gamma_2$ .  $\Gamma_2$  values are indicated on the curves.

From this, another necessary condition for steady-state solutions to exist is I>0. We have avoided including the equality which, according to Eq. (4), would lead to unbounded temperatures.

On assuming  $\int_1^h Q_1(s_1) ds_1 = 0$  and hence by Eq. (6)  $\int_1^h Q_2(s_2) ds_2 = 0$  also, coupling between the two equations represented by V in Eq. (14) would disappear, and the velocity in each loop would be determined by its own properties and heating functions. There would be no heat transfer along the heat exchanger since, from Eq. (12), we see that  $\theta_1(0) = \theta_2(0)$ , and then, from Eq. (9), the temperature on either side would be constant and equal.

#### IV. Specific Example

The general results of the previous section will be applied to the particular case of thermally coupled square loops as shown in Fig. 2. Loop 1 is heated from below and loop 2 is cooled from above, both nondimensional magnitudes being unity. Under these conditions, Eq. (14) becomes

$$\frac{v_1^2}{\Gamma_1} = \left[1 - \exp\left(\frac{v_1 + v_2}{v_1 v_2}\right)\right]^{-1} + \frac{v_1 v_2}{v_1 + v_2}$$
(18a)

and

$$\frac{v_2^2}{\Gamma_2} = 1 - \left[1 - \exp\left(\frac{v_1 + v_2}{v_1 v_2}\right)\right]^{-1} - \frac{v_1 v_2}{v_1 + v_2}$$
 (18b)

from which

$$\frac{v_1^2}{\Gamma_1} + \frac{v_2^2}{\Gamma_2} = 1 \tag{19}$$

If the heating and cooling zones had been interchanged, the right-hand side of Eq. (19) would have come out as -1. Consequently, steady-state solutions would be inadmissible under these circumstances without axial conduction.

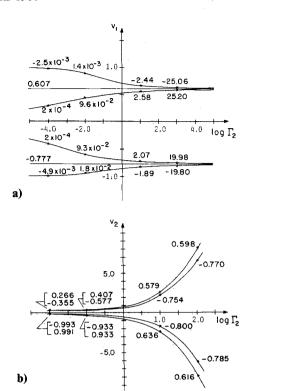


Fig. 4 Variation of a)  $v_1$  and b)  $v_2$  as functions of  $\Gamma_2$  for  $\Gamma_1 = 1$ .  $v_1$  and  $v_2$  values are indicated on the curves in a) and b), respectively.

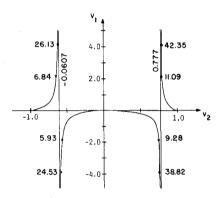


Fig. 5  $\nu_1-\nu_2$  plot for  $\Gamma_2=1$  and different  $\Gamma_1$ .  $\Gamma_1$  values are indicated on the curves.

Equations (18a) and (18b) were solved numerically using a Newton-Raphson method. Values of the velocities in a  $v_1$ - $v_2$  plot for fixed  $\Gamma_1$  and different  $\Gamma_2$  are shown in Fig. 3. Values of  $v_1$  and  $v_2$  as functions of  $\Gamma_2$  for  $\Gamma_1 = 1$  are shown in Figs. 4a and 4b, respectively. For fixed values of  $\Gamma_1$  and,  $\Gamma_2$ , there are four distinct solutions for  $v_1$  and  $v_2$ , one in each of the quadrants of Fig. 3.

The limits of the velocity  $v_1$  can be easily determined. As  $v_2$  tends to zero, we obtain from Eq. (18a) that

$$v_1^2 \rightarrow \frac{\Gamma_1}{1 - \exp(1/v_2)} \tag{20}$$

From this, and Eq. (18b), we see that

$$v_1 \to 0, \ \Gamma_2 \to 0$$
 as  $v_2 \to 0^+$  (21a)

and

$$v_1 \rightarrow \pm \sqrt{\Gamma_1}, \ \Gamma_2 \rightarrow 0$$
 as  $v_2 \rightarrow 0^-$  (21b)

On the other hand, for large values of  $v_2$ , we see from Eq. (18a) that

$$v_1^2 = \Gamma_1/[1 - \exp(1/v_1)] + v_1$$
 as  $v_2 \to \pm \infty$  (22)

the solutions to which are  $v_1 = 0.60681$  and -0.7772. These are thus the limits between which all the  $v_1$  solutions are forced to lie for arbitrary values of  $v_2$  and  $\Gamma_2$  as long as  $\Gamma_1 = 1$ .

Results are shown in Fig. 5 with  $\Gamma_2 = 1$  and for different  $\Gamma_1$ . This is similar to Fig. 3 except for the fact that the roles of  $v_1$  and  $v_2$  are reversed.

#### V. Conclusions

A simplified model of conjugate natural circulation loops has been studied. Axial conduction has been neglected, and the heat fluxes over both loops have been regarded as known except for the heat exchanger region where the heat transfer rate is proportional to the temperature difference. As an additional simplification, frictional forces are considered linear with fluid velocity. Under these conditions, four distinct sets of solutions can be obtained for the fluid velocities, as calculated for a particular example. These four velocities correspond to two in either direction for each loop. Which of these steady-states would occur would depend on initial conditions as well as their stability. If the heating flux of the first loop is fixed, variations of the heating in the other will change its own velocity but maintain the first loop velocity within finite limits.

Real systems should be looked at from the point of view not only of possible two-or three-dimensional motion but also with more general boundary conditions. The time-dependent problem is of interest also, especially regarding the stability of the different steady-state solutions. The present analysis merely outlines the complexity of the problem. It is expected that the simplifying assumptions made here have not altered the basic fact that is the existence of multiple steady-state solutions, but only facilitated their determination.

The simple analysis given in Ref. 6 can reasonably predict a steady-state velocity but not its multiplicity. This is because a temperature distribution is assumed which makes the resulting equation for the velocity, Eq. (1), linear. Multiplicity of steady-state solutions is a consequence of the nonlinear convective term in the energy equation (2). In order to study it, both velocity and temperature have to be considered as unknowns.

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